3

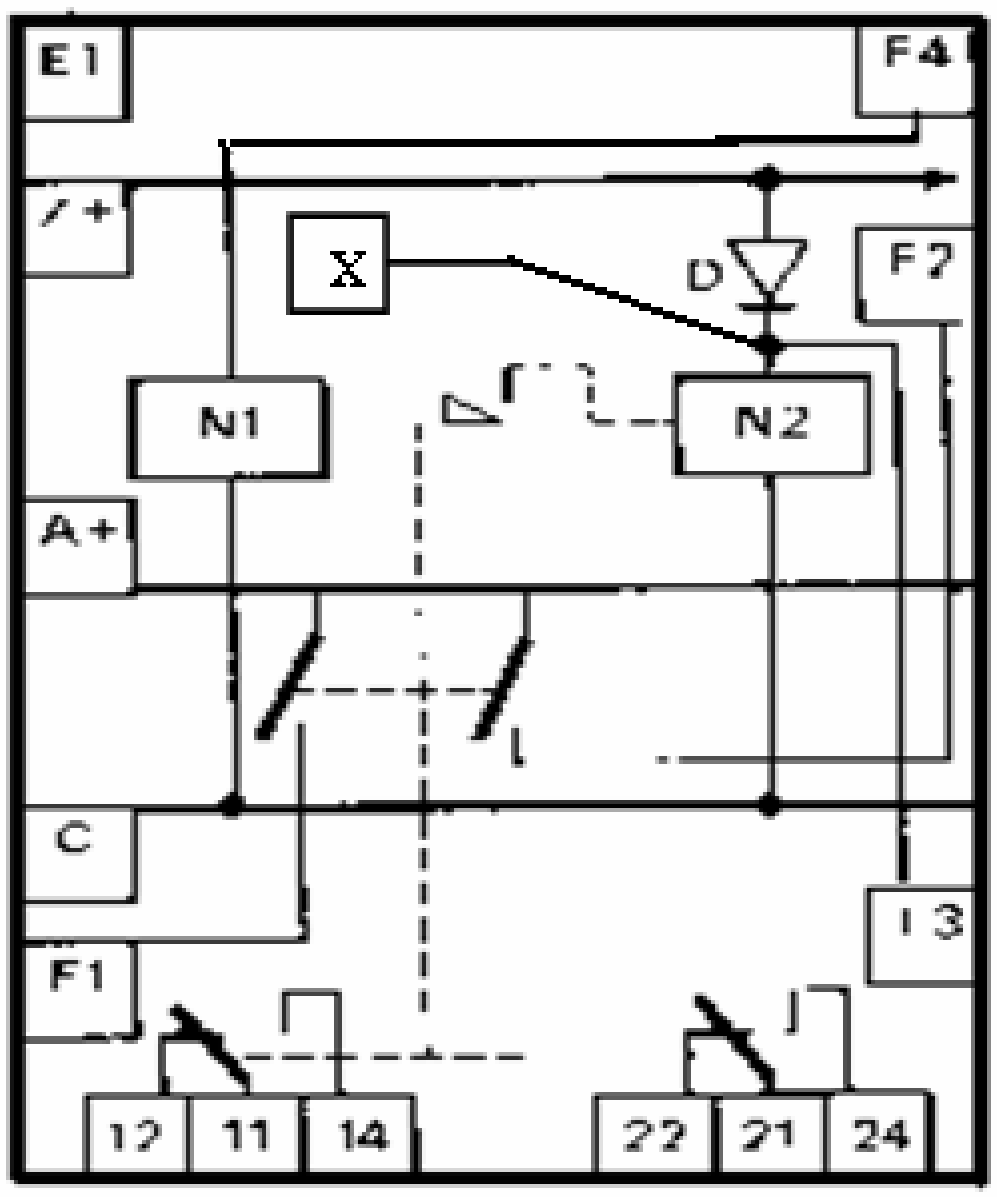
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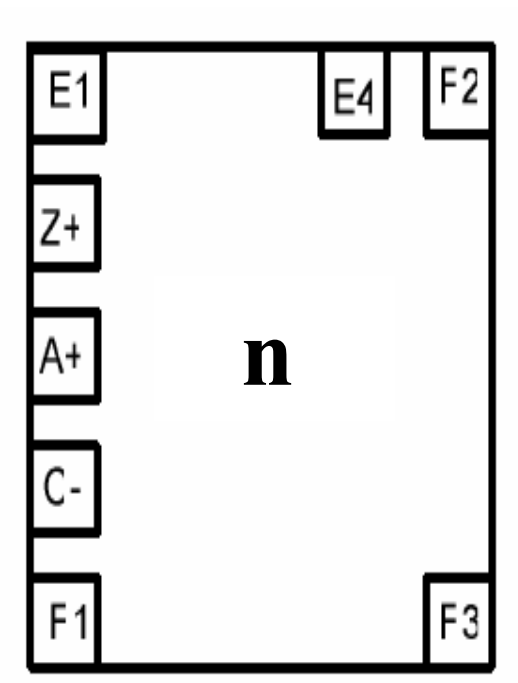
1 :

2

: 2 - 1

2 - 1 - 1





المقيـــاس n :

..... : N2 ..... : N1

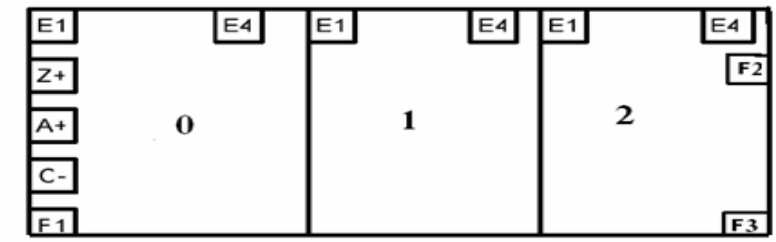
..... : Z+ ..... : A, C

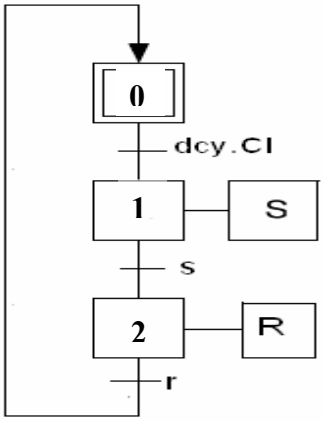
..... : E1. ..... : F1

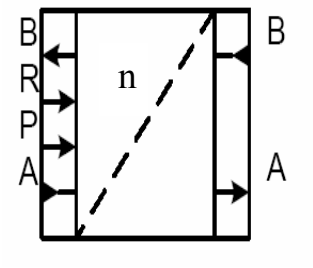
..... :X..... : E4 و E1 بين

..... : F3..... : F2

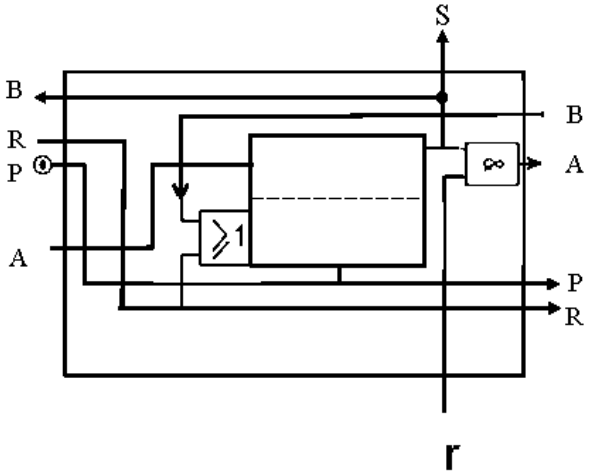
..... :(24 ⊂Z1) ⊂(22 ⊂Z1) ⊂(11،14) ⊂(11،12)







المقيـــاس n :

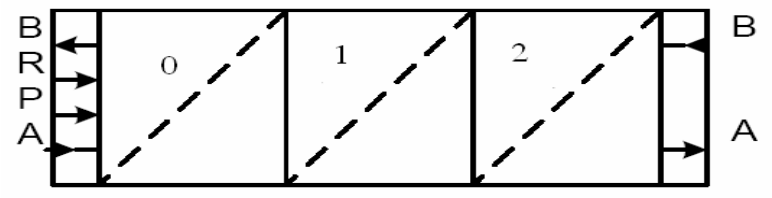


..... : R ..... : P

..... : B ..... : A

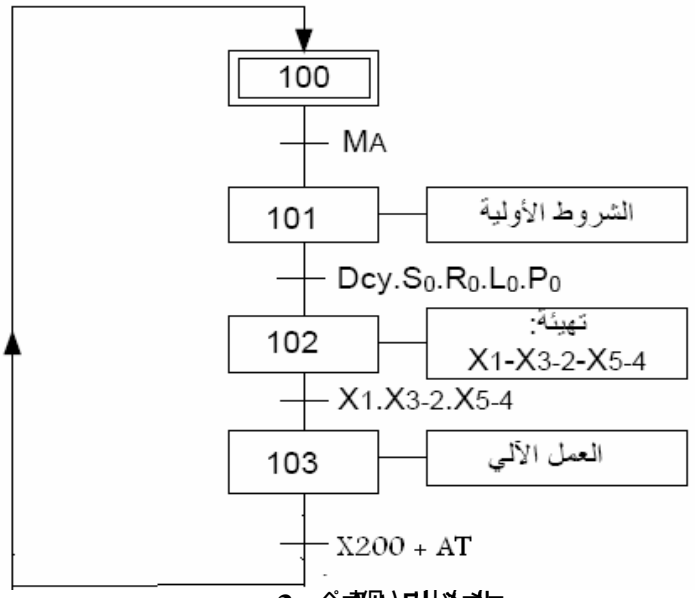
..... : r ..... : S

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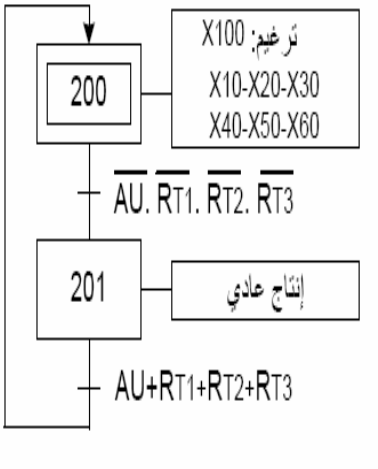


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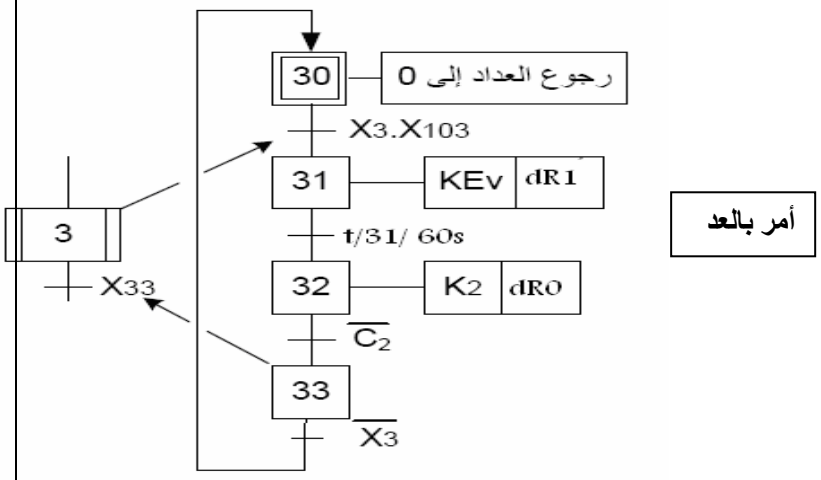
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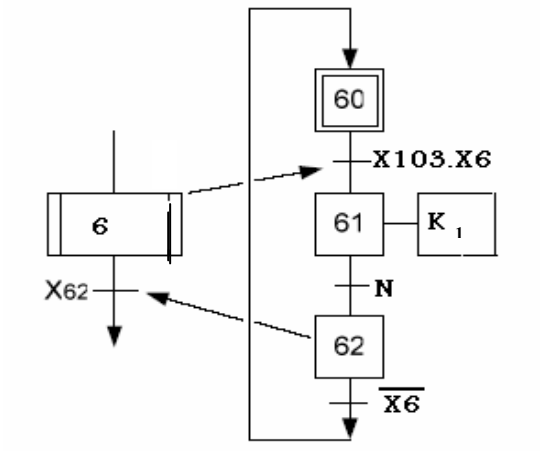


3



6





6 pA3

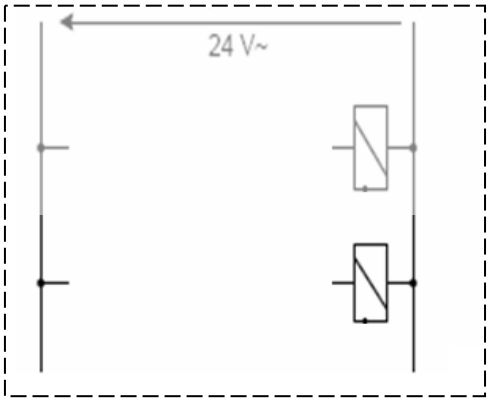
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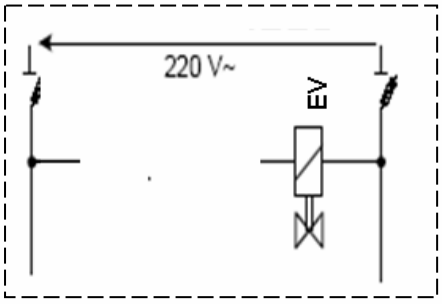
	N
	C_2

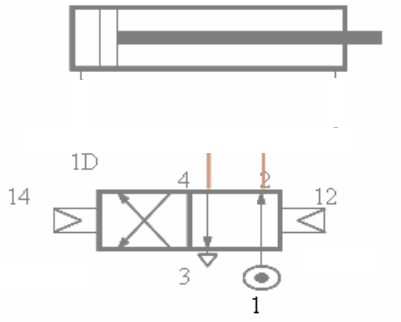
24v~ , K_{Δ}, K_Y , K_1	3 kW~	M1
24v~ K_2	3 kW~	M2
24v~ KEv	220 V~	EV
dR1 , dR0		R

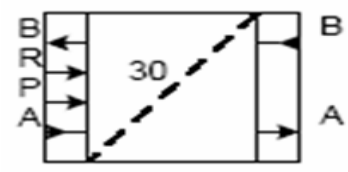
« R » - "EV" - « M2 » .

M2 EV EV R



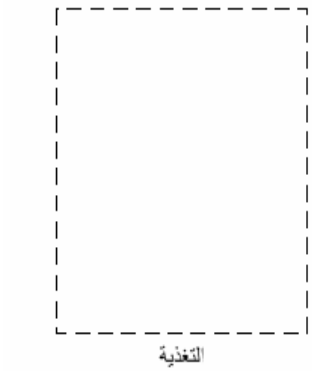


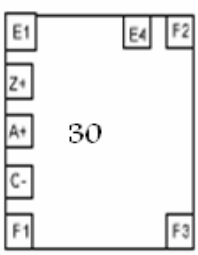


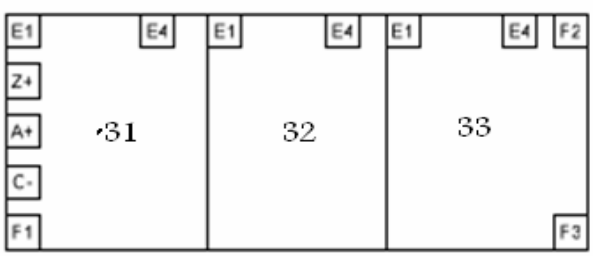




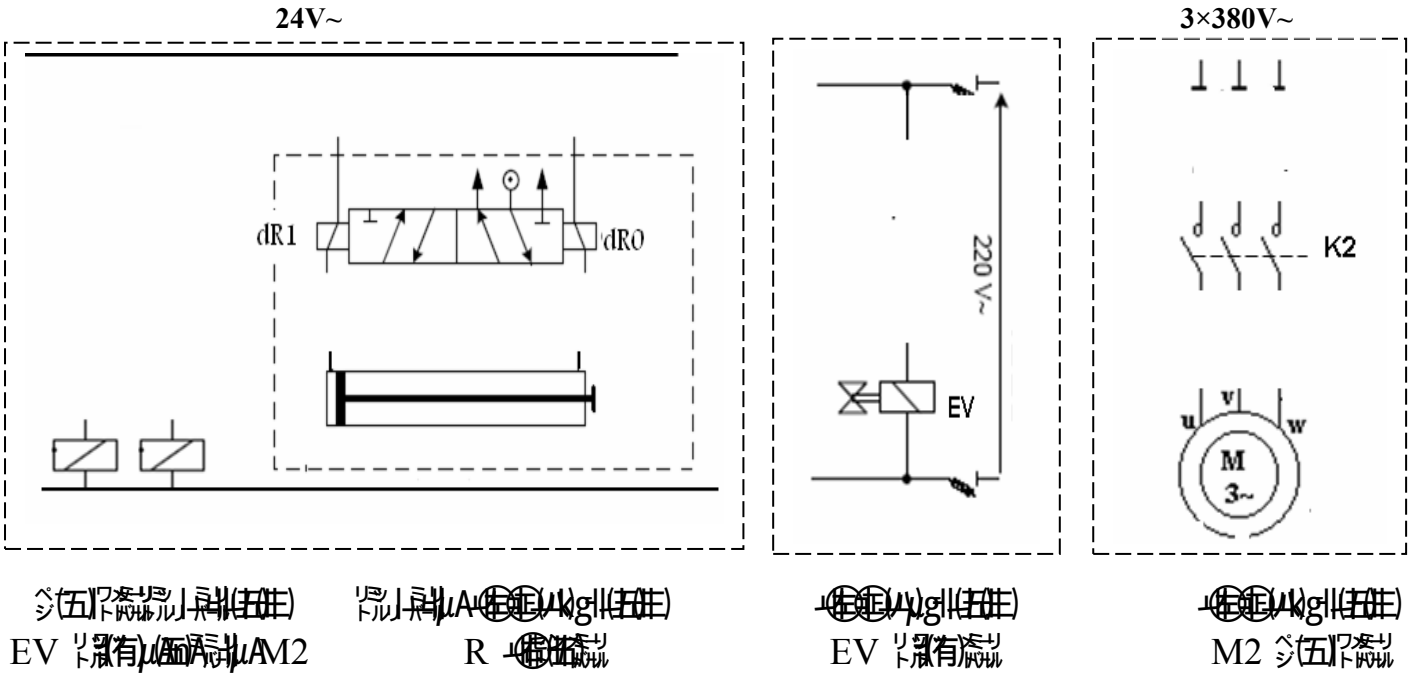
« R » - "EV" - « M2 » .



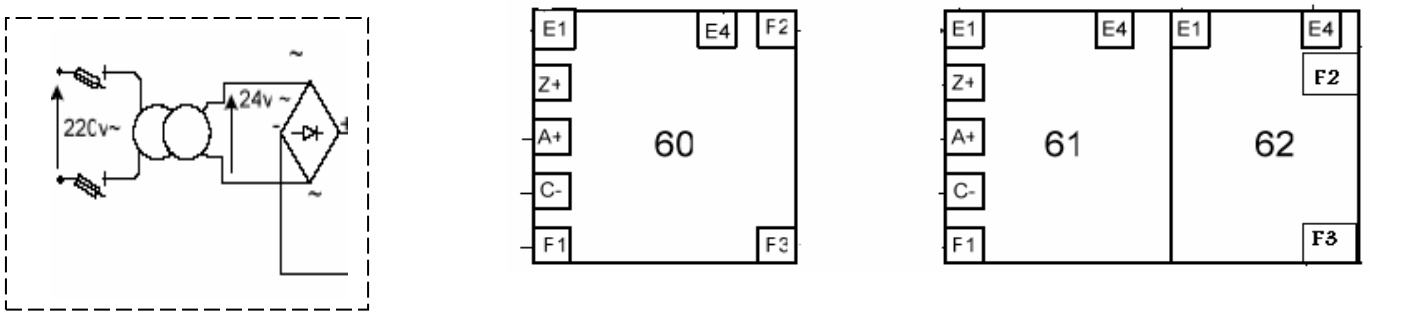




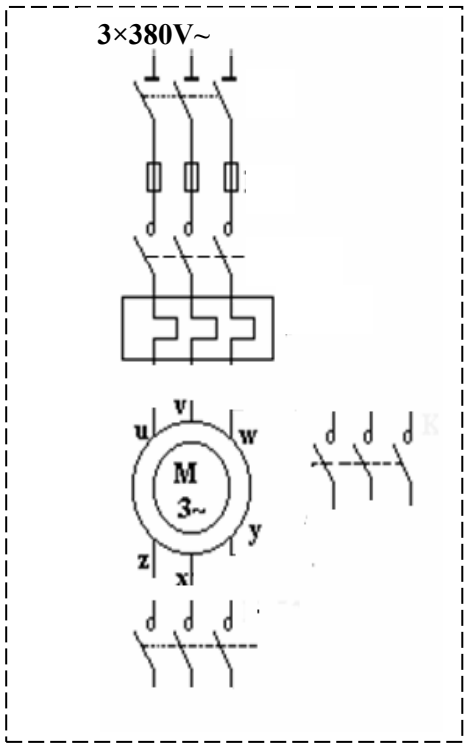
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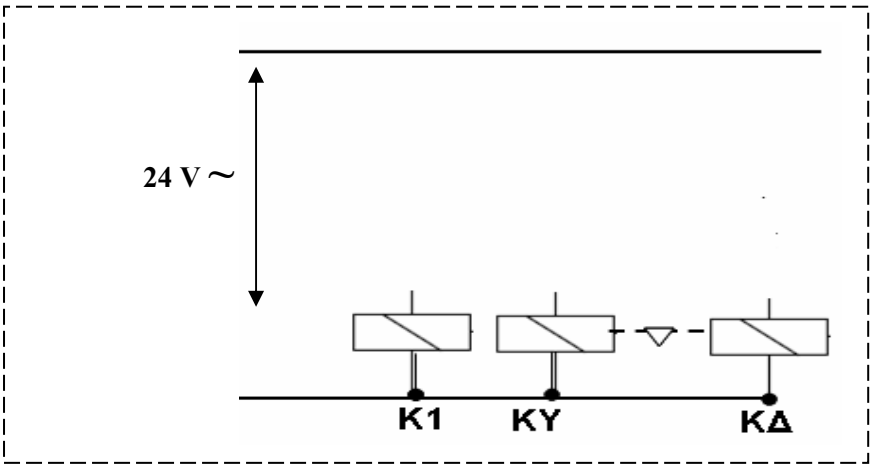
. « M1 » ページ五のワイヤリング・ダイヤグラムを参照してください (6) 手動モードでは、3 ×



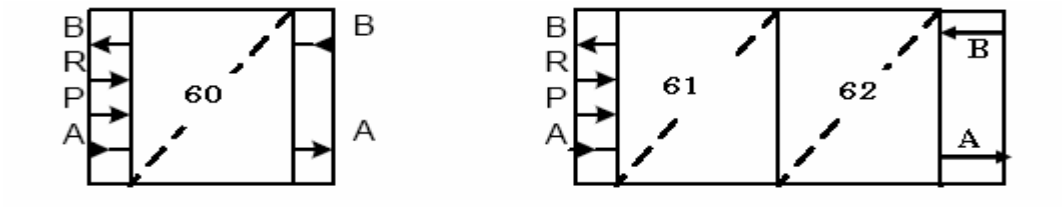
دارة الإستطاعة للمحرك M1



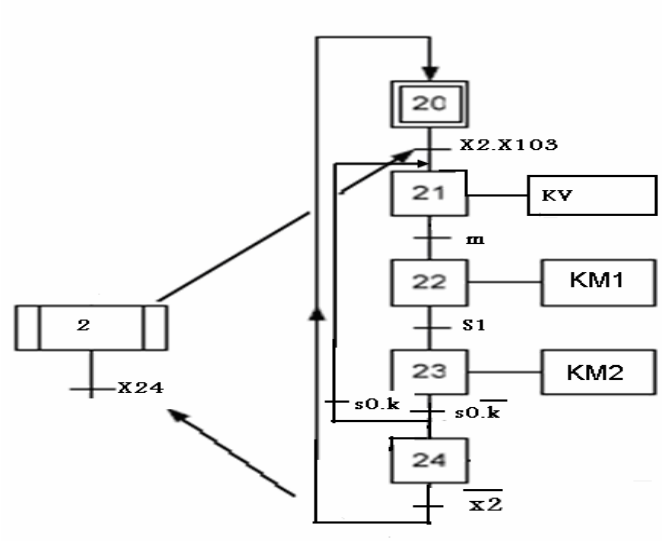
M1 パイロット・ワイヤリング・ダイヤグラム

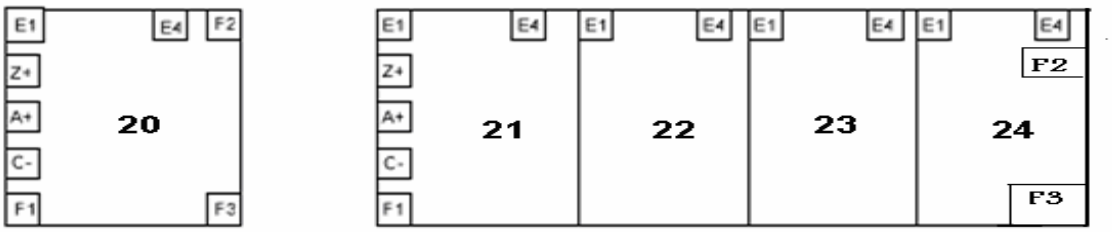


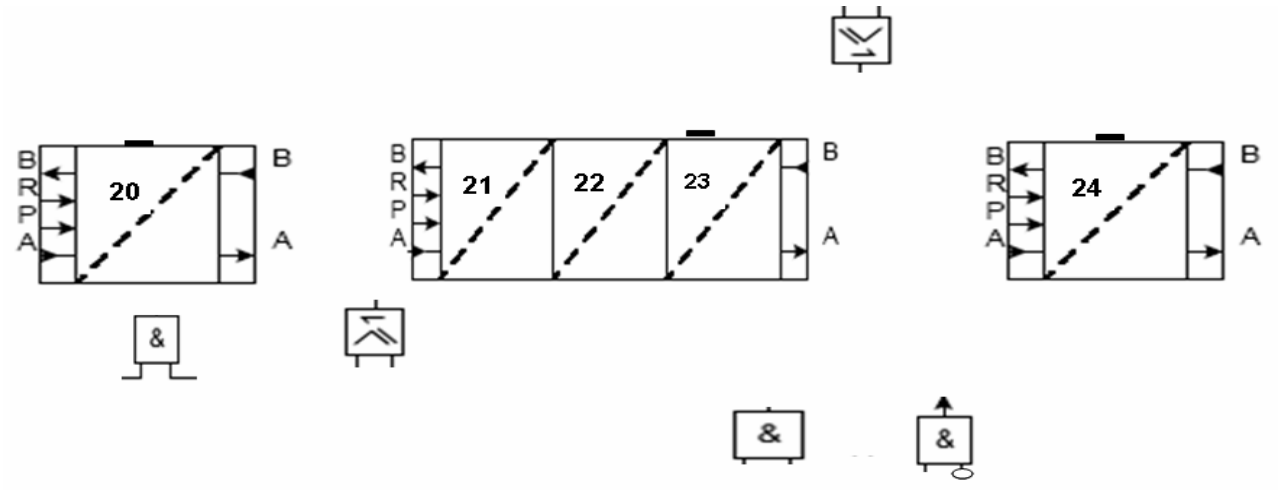
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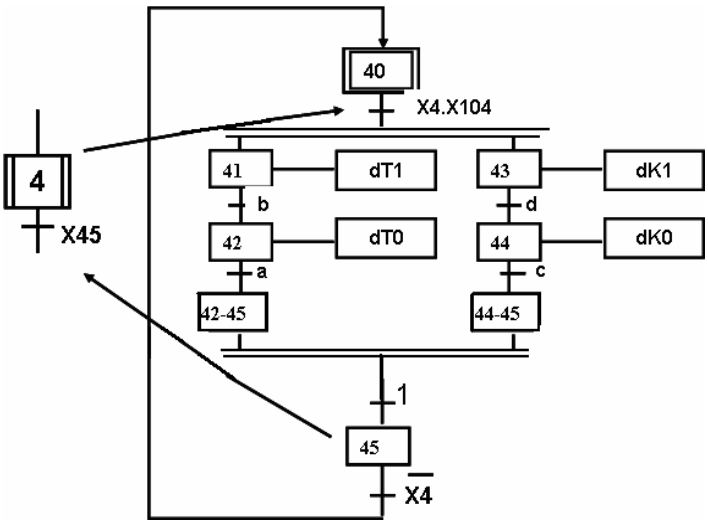
- **نشـــــاط 2** : أرسم دارة المعقب الهوائي ثم الكهربائي للأشغولة التالية :

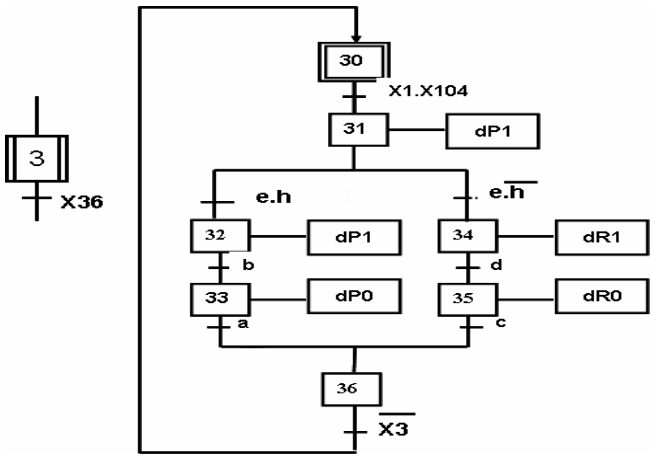


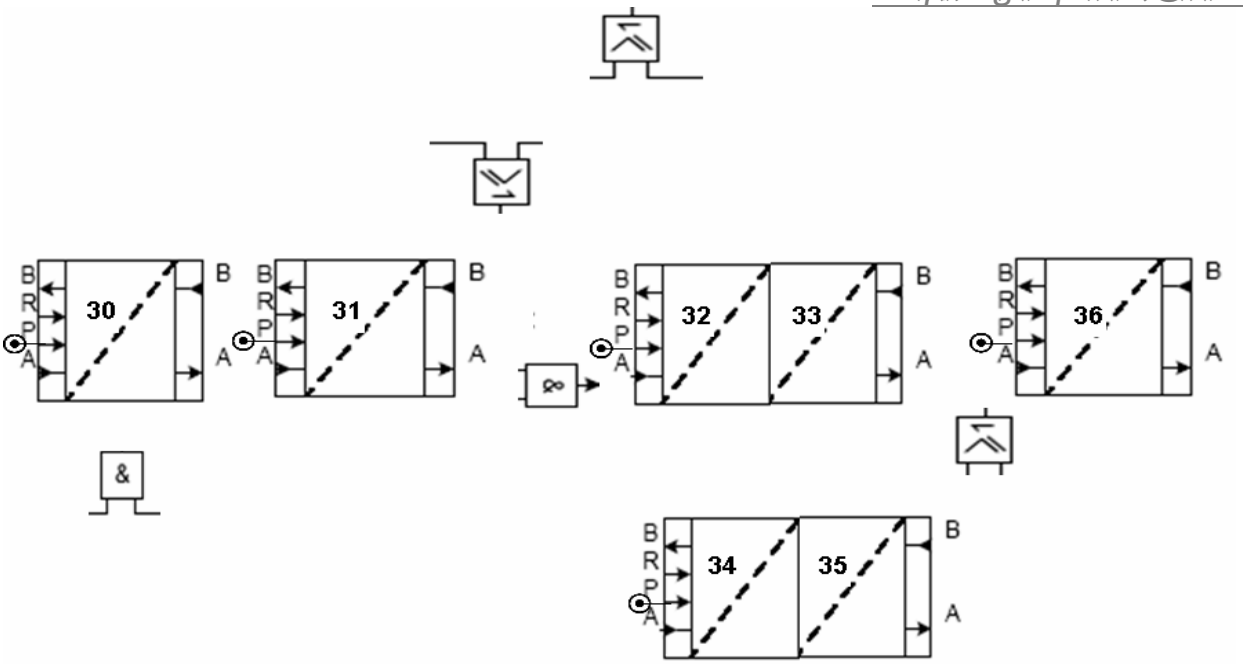


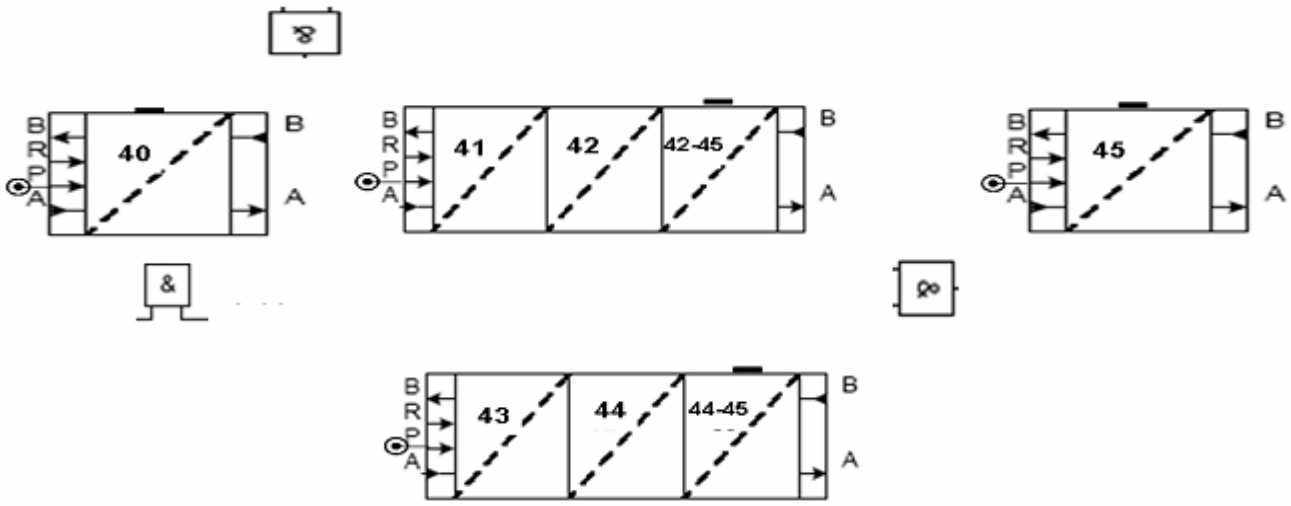


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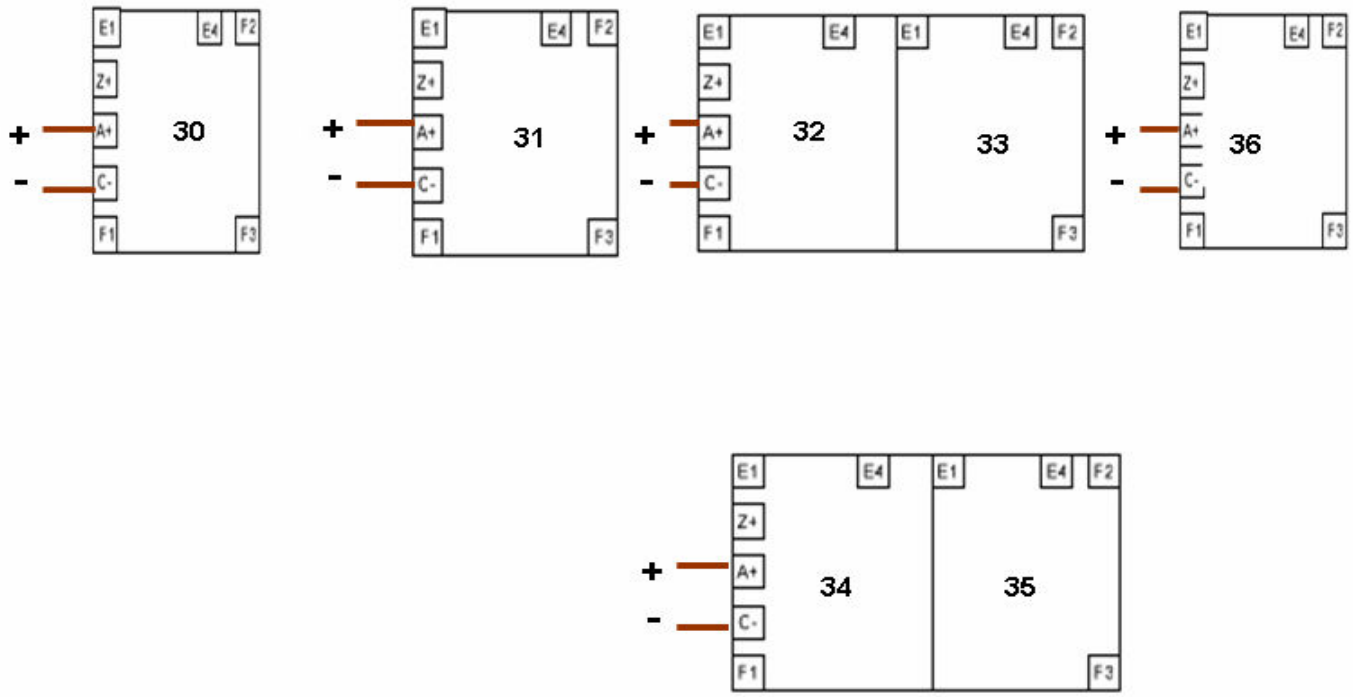

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b
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42
dT0
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dK0
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X45
1
45
X4


3
X36
30
X1.X104
31
dP1
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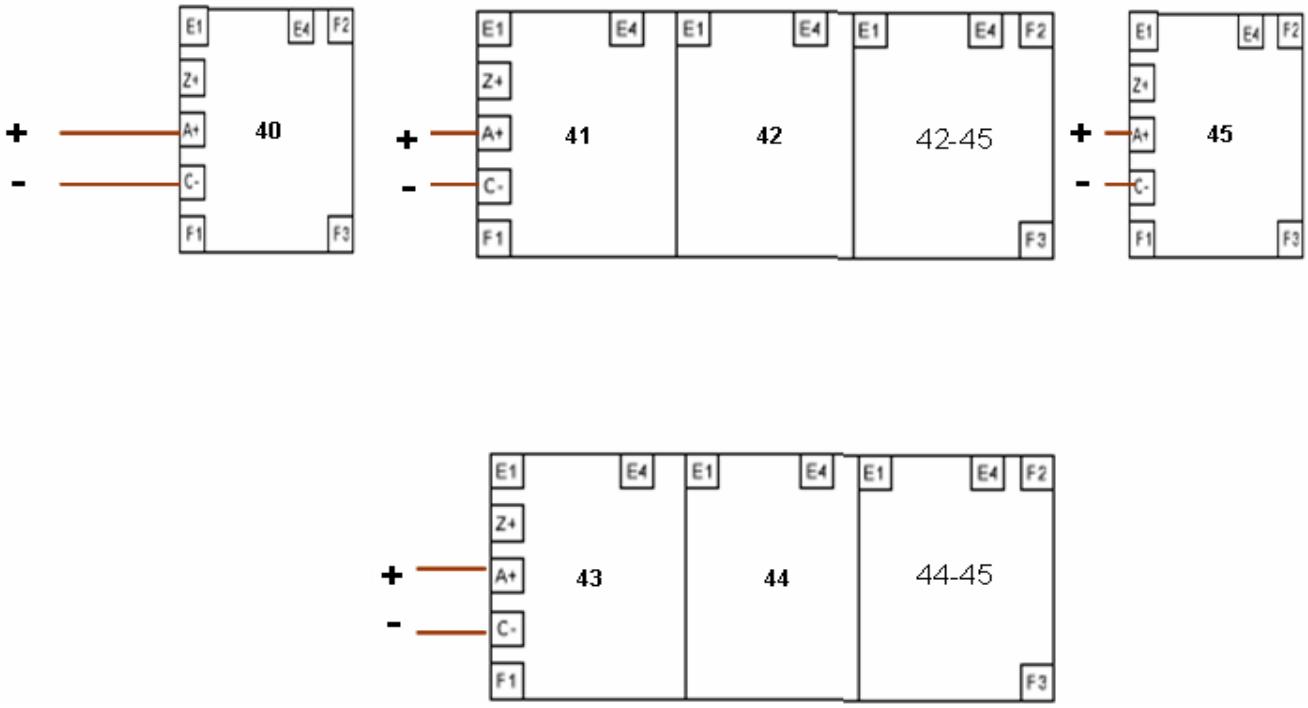

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P
A

- الشكل 3: مخطط توصيل المحرك ثلاثي الأطوار



- الشكل 4: مخطط توصيل المحرك ثلاثي الأطوار



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